

Designing Broad-Band Patch Antennas Using the Sequential Quadratic Programming Method

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Abstract—The utility of numerical codes is greatly enhanced if they can be used in design, a situation that typically involves iterative optimization algorithms. An attractive way is to use gradient-based algorithms developed for solving nonlinear programming (NLP) problems. In this letter, we examine the performance of a general sequential quadratic programming (SQP) optimization algorithm for designing patch antennas in conjunction with a finite-element boundary-integral code.

Index Terms—Microstrip antennas.

I. INTRODUCTION

ANTENNA design involves the selection of the physical antenna parameters to achieve optimal gain, pattern performance, VSWR, bandwidth, and so on, subject to specified constraints. Over the past ten years, sophisticated computer codes have been developed for antenna analysis [1]–[3] based on a variety of popular methods. By and large, these codes have not been extended to include design capabilities primarily because of their complexity and nonlinearity with respect to the physical properties of the antenna (material constants, dimensions, feed location, and type, etc.). Some design algorithms have been proposed but these are applicable to specialized antenna shapes and do not address the general antenna optimization problem [4].

Recently, genetic algorithms (GA's) have been examined for array design and absorber optimization [5]–[7]. However, GA's, although robust, require large number of function evaluations to complete the optimization study. Also, GA's are more suitable for discrete variable problems. In contrast, antenna simulations rely on complex computationally intensive codes, which generate continuous functions. It may, therefore, be impractical to generate a sufficiently large sample space for carrying out an optimization study using GA's.

An alternative optimization algorithm is the sequential quadratic programming (SQP) method, suitable for continuous nonlinear objective functions such as the input impedance, gain, pattern shape, etc. with both equality and inequality constraints. Convergence is typically achieved in a few iterations and, therefore, their interface with rigorous (but expensive) numerical antenna analysis codes is much more practical. SQP and other similar algorithms are routinely used for large structural design problems involving finite-element

analysis [8] and, thus, we can benefit from the extensive experience available in other disciplines.

In this letter, we examine the performance of a general SQP code [9] for designing patch antennas in conjunction with a finite-element boundary-integral code [10]. Both are rigorous general-purpose codes. The main point of the paper is to examine the suitability of SQP for antenna parameter optimization to achieve the design objectives subject to constraints. We will illustrate the performance of the optimizer using a few illustrative examples from simple to more complex.

II. SEQUENTIAL QUADRATIC PROGRAMMING ALGORITHM DESCRIPTION

SQP is a gradient-based class of methods that became prominent in the late 1970's [11]. They are considered the most efficient general-purpose nonlinear programming algorithms today. The basic principle of sequential approximations is to replace the given nonlinear problem by a sequence of quadratic subproblems that are easier to solve.

Consider the equality constrained problem

$$\begin{aligned} \min f(\mathbf{x}) \\ \text{subject to } \mathbf{h}(\mathbf{x}) = \mathbf{0} \end{aligned} \quad (1)$$

where \mathbf{x} is the design variable vector, $f(\mathbf{x})$ is the objective function, and $\mathbf{h}(\mathbf{x})$ is the vector of equality constraints. Using a Lagrange–Newton method (see, for example, [11]), at the k th iteration, we have

$$\begin{bmatrix} \mathbf{W}_k & \mathbf{A}_k^T \\ \mathbf{A}_k & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{s}_k \\ \lambda_{k+1} \end{bmatrix} = \begin{bmatrix} -\nabla f_k^T \\ -\mathbf{h}_k \end{bmatrix} \quad (2)$$

where $\mathbf{W} = \nabla^2 f + \lambda^T \nabla^2 \mathbf{h}$, $\mathbf{A} = \nabla \mathbf{h}$, and λ is the vector of Lagrange multipliers. Solving the above equations iteratively, we obtain the iterates $\mathbf{x}_{k+1} = \mathbf{x}_k + \mathbf{s}_k$ and λ_{k+1} which should eventually approach \mathbf{x} and λ , the optimal values.

We observe that the above equation can be viewed as the first-order optimality (Karush–Kuhn–Tucker) conditions for the quadratic model

$$\begin{aligned} \min q(\mathbf{s}_k) = f_k + \nabla_{\mathbf{x}} L_k \mathbf{s}_k + \frac{1}{2} \mathbf{s}_k^T \mathbf{W}_k \mathbf{s}_k \\ \text{subject to } \mathbf{A}_k \mathbf{s}_k + \mathbf{h}_k = \mathbf{0} \end{aligned} \quad (3)$$

where $\nabla_{\mathbf{x}} L_k = \nabla f_k + \lambda_k^T \nabla \mathbf{h}_k$. Solving the quadratic programming subproblem (3) gives the same \mathbf{s}_k and λ_{k+1} as solving (2) and thus the two formulations are equivalent. The values of \mathbf{x} and λ can be obtained from solving a sequence

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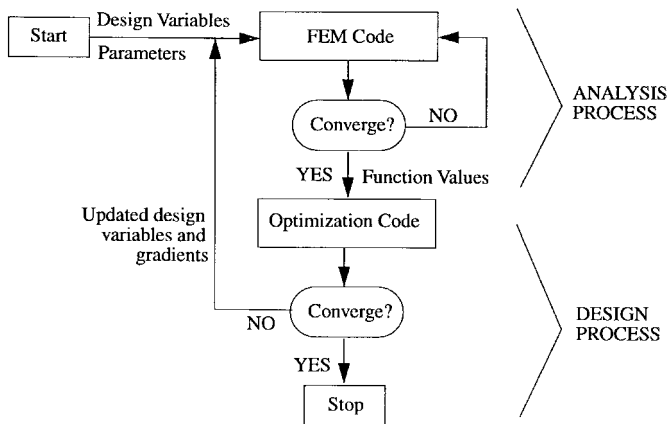


Fig. 1. Flow chart of SQP combined with FEM.

of quadratic programming (QP) subproblems, hence the name SQP methods for the relevant algorithms.

Proper convergence properties are achieved with some modifications on this basic SQP algorithm. We may view \mathbf{s}_k as a search direction and define the iterate as $\mathbf{x}_{k+1} = \mathbf{x}_k + \alpha_k \mathbf{s}_k$ where the step size α_k is introduced and computed by minimizing an appropriate merit function along the search direction. The QP subproblem can be solved efficiently by well-developed QP solvers, based, for example, on projection or augmented Lagrangian methods. Using an active set strategy, problems with both equality and inequality constraints can be solved.

III. COMBINING SQP WITH THE FINITE-ELEMENT METHOD

In the next section, we give two examples of microstrip antenna optimization using the SQP algorithms. For the calculation of the objective function, a hybrid finite-element algorithm is used to compute electromagnetic scattering and radiation by an open three-dimensional rectangular cavity recessed in an infinite ground plane [10]. The cavity may support microstrip patch or slot antennas and may be filled with layered dielectric material. The problem is formulated using the finite-element boundary-integral method and the resulting system of equations is solved via the biconjugate gradient method. Besides different layers of dielectrics, the cavity may also have lumped loads, probe feeds, and short circuit pins. The flow chart of the whole process is shown below in Fig. 1.

Accordingly, the finite-element method (FEM) code first computes the objective function using an initial set of antenna parameters which is used by the optimizer to determine the new search direction and step size. The process is repeated until convergence within the given tolerance is achieved.

IV. EXAMPLE APPLICATIONS

A. Probe-Fed Dual Patch

A number of techniques have been suggested and implemented to improve the bandwidth of the microstrip patch antenna. One of them is stacking patches horizontally or vertically [12]. Several parameters (size of patches, substrate

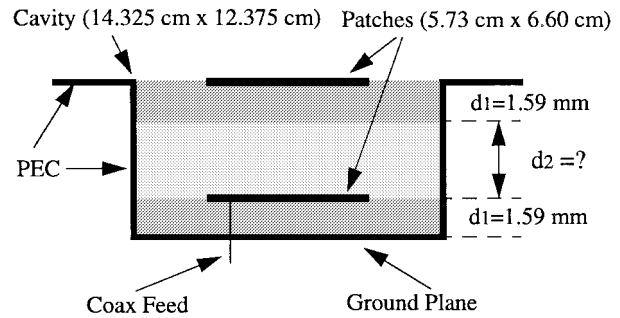


Fig. 2. Geometry of the dual-patch antenna.

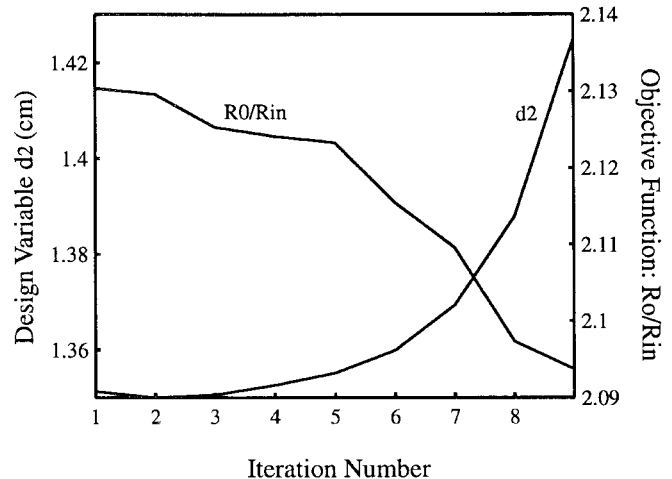


Fig. 3. Iteration history for the optimization of the dual-patch antenna.

thicknesses, feed locations, etc.) can be used to maintain a low voltage standing wave ratio (VSWR) over a given frequency range. For our purposes, we choose the VSWR to be around two, which corresponds to a return loss of about 3 dB. Thus, we can write the problem statement as $R_0/R_{in} < 2$ where R_0 refers to the input resistance at resonance and R_{in} is the corresponding resistance at nearby frequencies.

Fig. 2 illustrates the configuration of the stacked antenna under investigation. The top and lower substrates have a dielectric constant of $\epsilon_r = 2.2$ and thickness $h = 1.59$ mm and the driven patch is designed to operate at 1.53 GHz. The middle substrate has a relative permittivity of $\epsilon_r = 1.1$. We wish to find the optimum length, width, and separation of the patches to achieve a 15% bandwidth. As a starting point in the optimizer, we use the values from the cavity model [13], i.e., $L = 5.73$ cm and $W = 6.60$ cm, respectively. The top patch was chosen to have the same dimensions.

After nine iterations of the optimizer, a value of $d_2 = 14.25$ mm was determined which delivers a bandwidth of 15%. The VSWR is less than 2.09 within the entire bandwidth. The center frequency is 1.53 GHz, if the patch size is 5.73 cm \times 6.6 cm and Fig. 3 gives the iteration history for the dual-patch optimization.

B. Slot-Fed Dual Patch

There are many ways to improve impedance bandwidth such as impedance matching and multiple resonances [14].

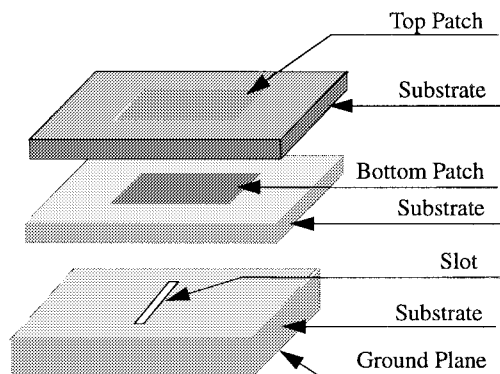


Fig. 4. Three-dimensional view of the stacked patches with aperture.

The latter (borrowed from tuned electronic amplifier design) is a popular approach and introduces additional resonant patches to provide two or more closely spaced resonances. The design principle of the previous example falls into this category. However, that example dealt with only a single-variable optimization. To improve the bandwidth for a dual-patch configuration, we now consider a multivariable optimization.

The structure of the stacked-patch antenna is shown in Fig. 4. The size of the top patch is slightly larger than that of the bottom patch to get a better bandwidth and a slot feed is put below the bottom patch. Among all geometric parameters which are sensitive to the design, we choose three for optimization. Specifically, the slot length, and the two substrate thicknesses were chosen for optimization with the goal of achieving a bandwidth more than 15% with VSWR < 2 . The dimensions of the other parameters are given below:

TOP PATCH: length = 3.89 mm/ width = 5 mm

thickness to be decided; $\epsilon_r = 2.33$;

BOTTOM PATCH: length = 3.5 mm

width = 4.5 mm

thickness to be decided; $\epsilon_r = 2.2$;

SLOT FEED: slot-width = 0.5 mm

slot length to be decided;

GROUND SUBSTRATE: thickness = 0.508 mm;

$\epsilon_r = 2.2$.

The stacked patches are residing in a cavity 1.4 cm \times 1.8 cm in size.

The problem statement is the same as in the last example, i.e. $\min R_0/R_{in}$ plus some size constraints, and the antenna analysis simulation is also based on the same hybrid finite-element code. After six iterations, the SQP optimizer found the following optimal values for the three unknown parameters: thickness of the substrate supporting top patch = 0.85 mm; thickness of the substrate supporting the bottom patch = 0.55 mm; and slot length = 4 mm. The performance of this antenna is shown in Fig. 5, with a VSWR equal to only 1.414 over an 18% bandwidth.

V. CONCLUSION

The advantages of the SQP algorithm are fast convergence and reduced number of function evaluations. This is attractive

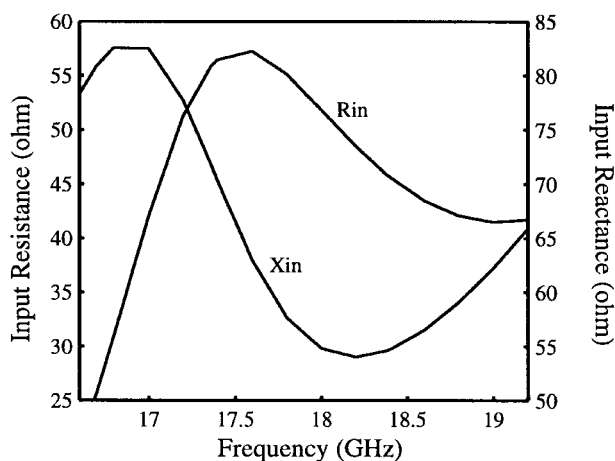


Fig. 5. Performance of the optimized dual patch-slot antenna.

when expensive computations are needed within the optimization loop. SQP achieves its speed by restricting its search in a more narrow range (local optimization) than genetic algorithms and by making use of gradient information. This is suitable for a large class of antennas where a limited range of parameter values is sufficient for good performance.

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